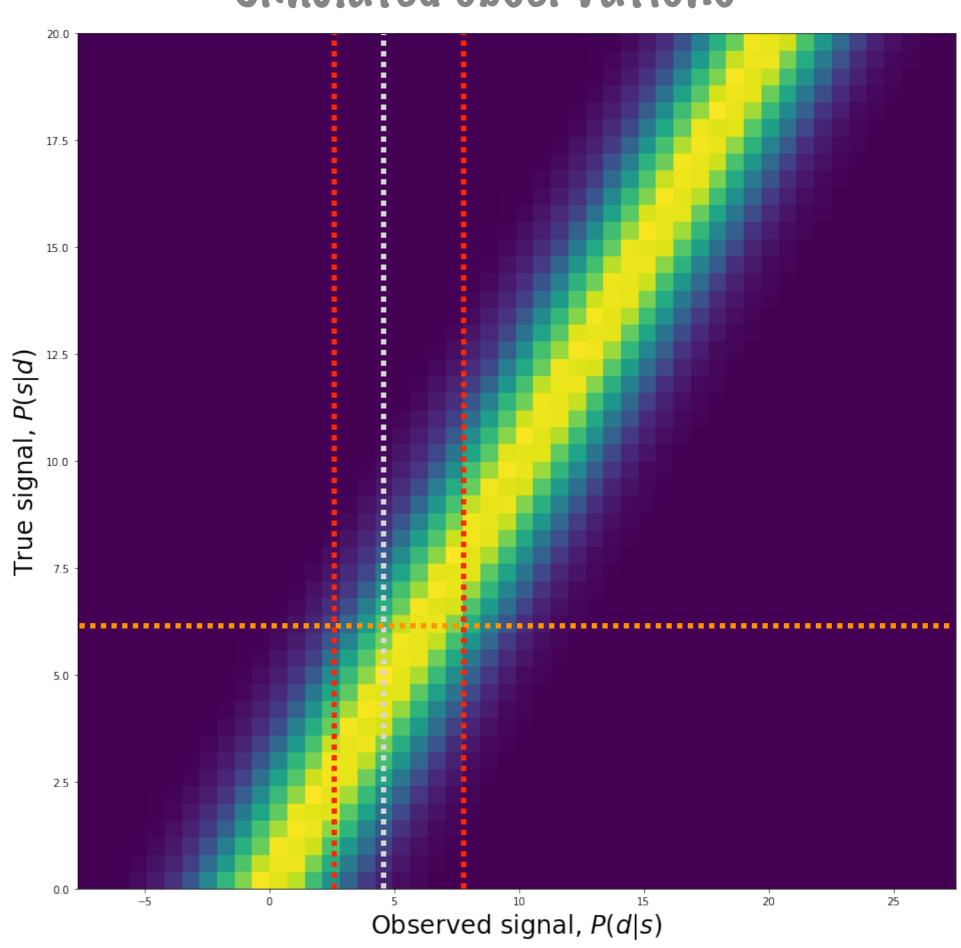
## Cautionary examples of statistical errors

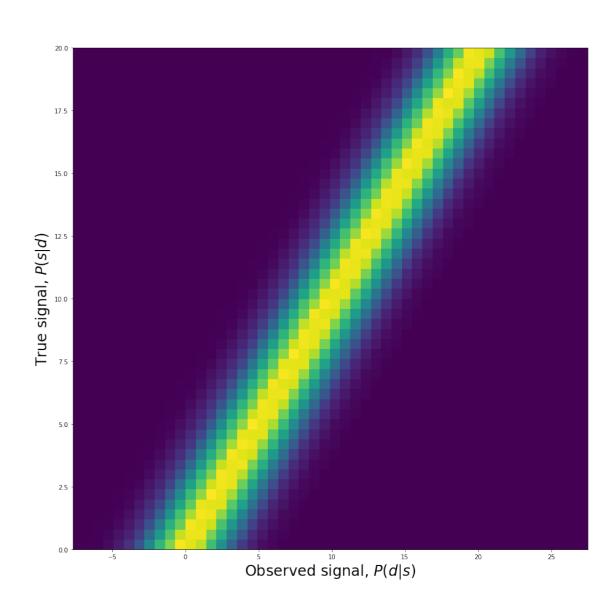
Miguel F. Morales Bryna Hazelton Review: how to calculate a confidence interval/upper limit

# Simulated observations



### How to calculate

- Simulate: determine  $P(d \mid s)$  for every signal value
- Signal injection: take signal free data and inject a face signal to see what it looks like; repeat for every signal value
- Use math: Bayes' theorem



## Bayes' theorem

$$P(s \mid d) = \frac{P(d \mid s)P(s)}{P(d)}$$

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Normalization

## Bayes' theorem

$$P(s \mid d) = \frac{P(d \mid s)P(s)}{P(d)}$$

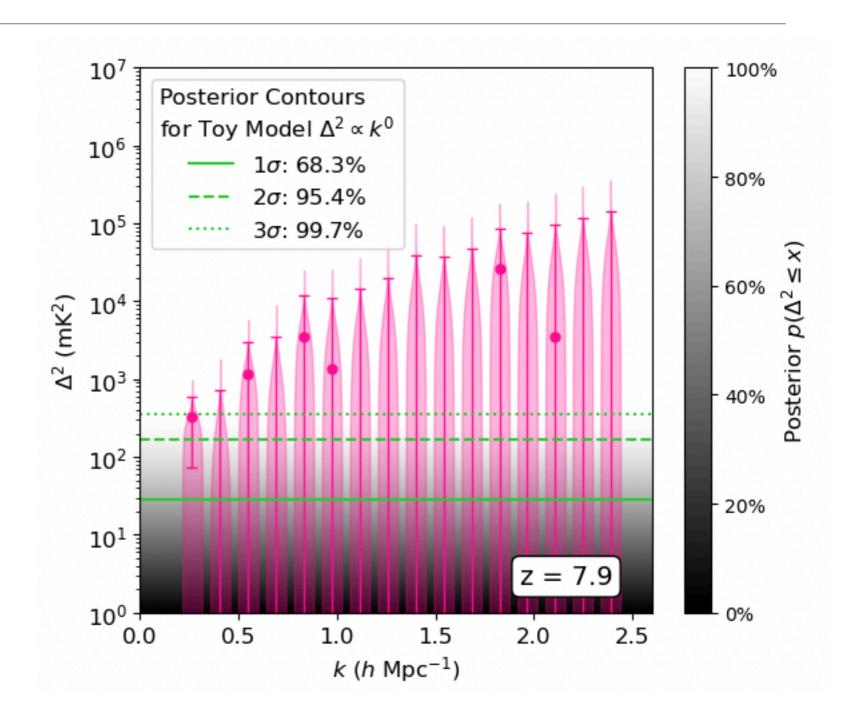
$$P(s \mid d) = \frac{P(d \mid s)P(s)}{P(d)}$$
Normalization

- Always interpreting in the framework of a model
  - May be generic/data driven, e.g. a 'top hat pulse'
- Prior necessary to invert
  - Powerful when driven by knowledge
  - Dangerous when driven by assumptions

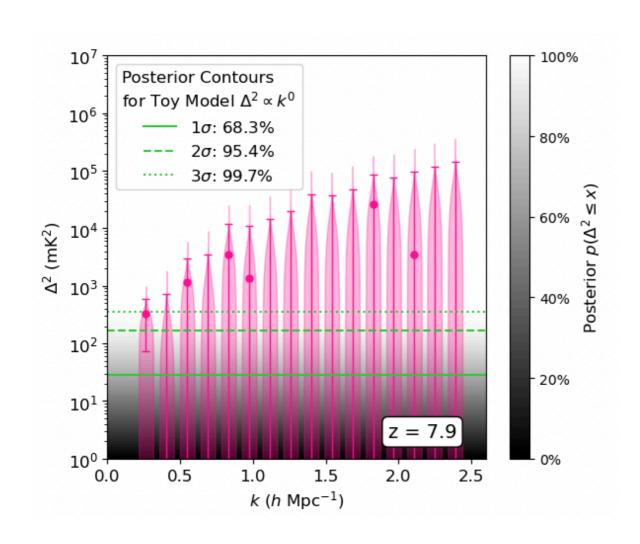
Implicit or explicit logarithmic priors

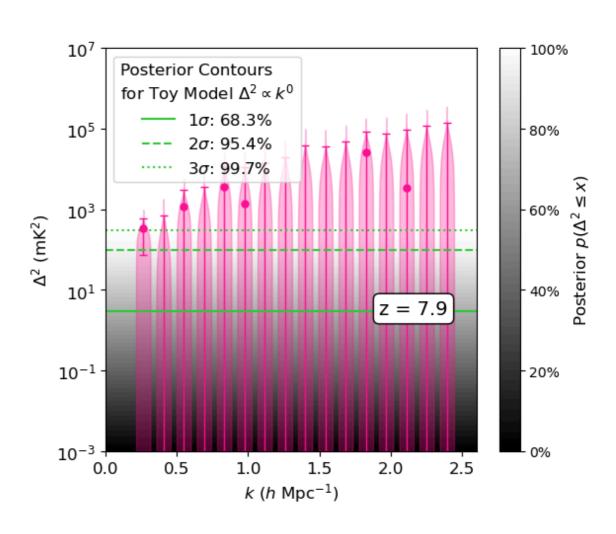
## Case study

- Combined upper limit combining many limits
- Use Bayes' theorem to invert
- Logarithmic prior



## I asked to change lower bound from 1 to 1e-3

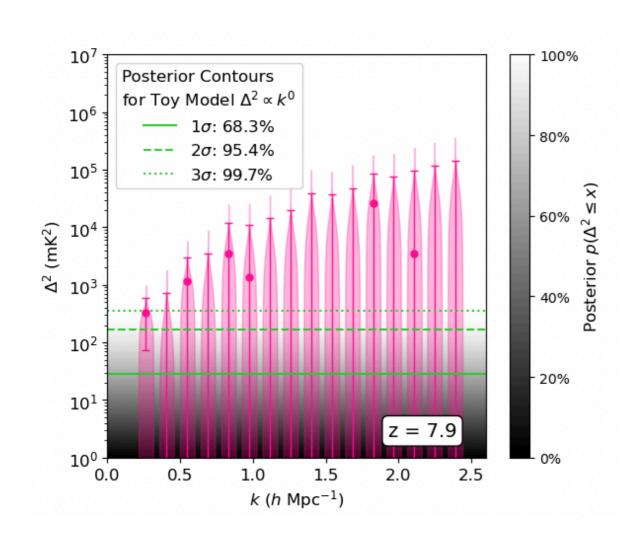


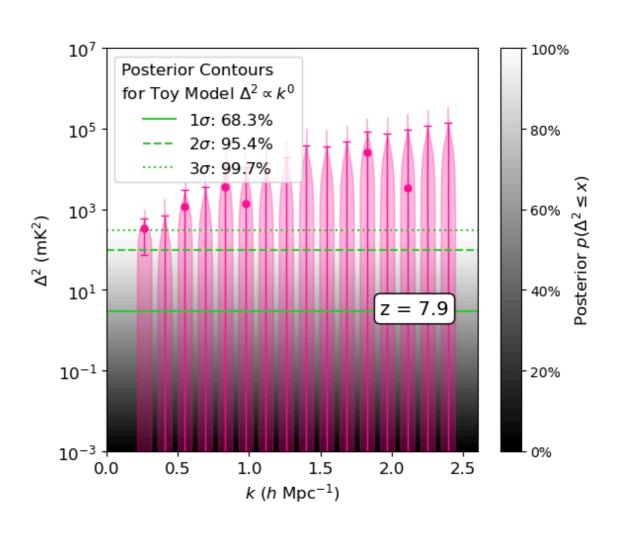


 $2\sigma$  upper limit:  $16.7 \text{ mK}^2$ 

 $2\sigma$  upper limit: 9.7 mK<sup>2</sup>

# Moving *lower* prior bound by <1 mK<sup>2</sup> changed *upper* limit by 7 mK<sup>2</sup>!

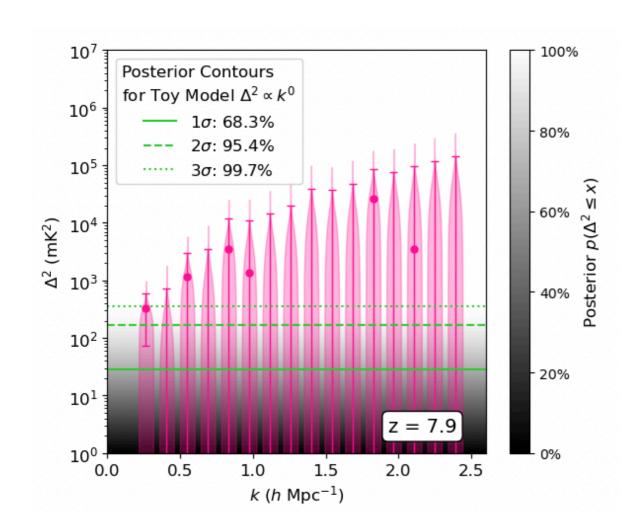




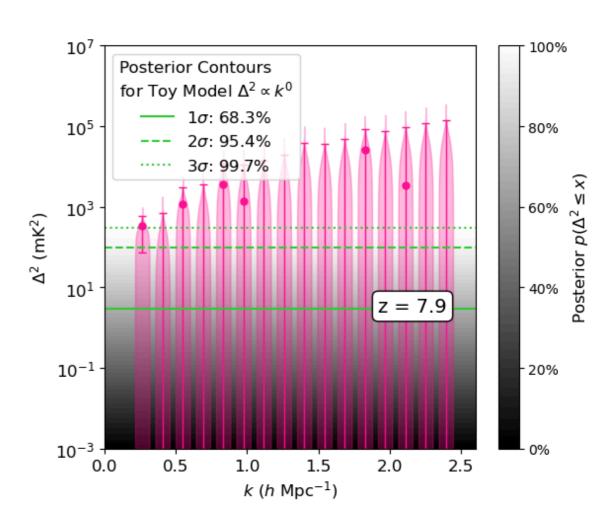
 $2\sigma$  upper limit: 16.7 mK<sup>2</sup>

 $2\sigma$  upper limit: 9.7 mK<sup>2</sup>

## Which was right?



 $2\sigma$  upper limit:  $16.7~{\rm mK}^2$ 



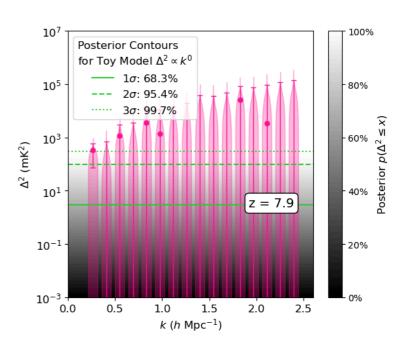
 $2\sigma$  upper limit: 9.7 mK<sup>2</sup>

## Neither!

$$P(s \mid d) = \frac{P(d \mid s)P(s)}{P(d)}$$

## Log prior in linear space





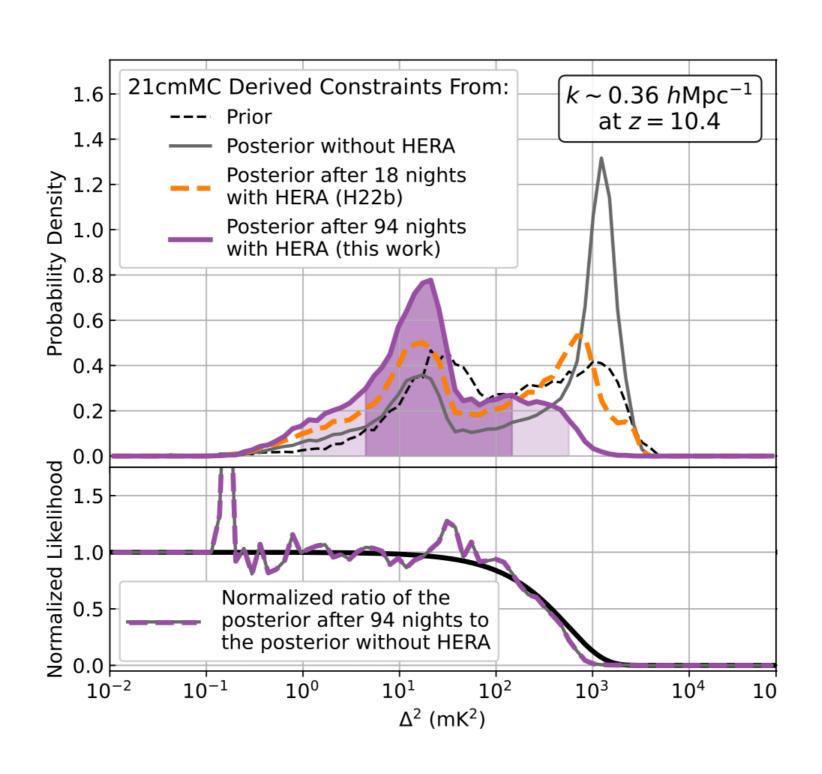
**Normalization** 

## Logarithmic priors are shockingly dangerous

- A lower value must be chosen so  $\int P(s) = 1$
- Upper and lower values tightly linked by normalization requirement
- Most common bad statistical mistake I see
- Rule of thumb: never use logarithmic priors

Asking the wrong question

## Misusing Bayes' theorem



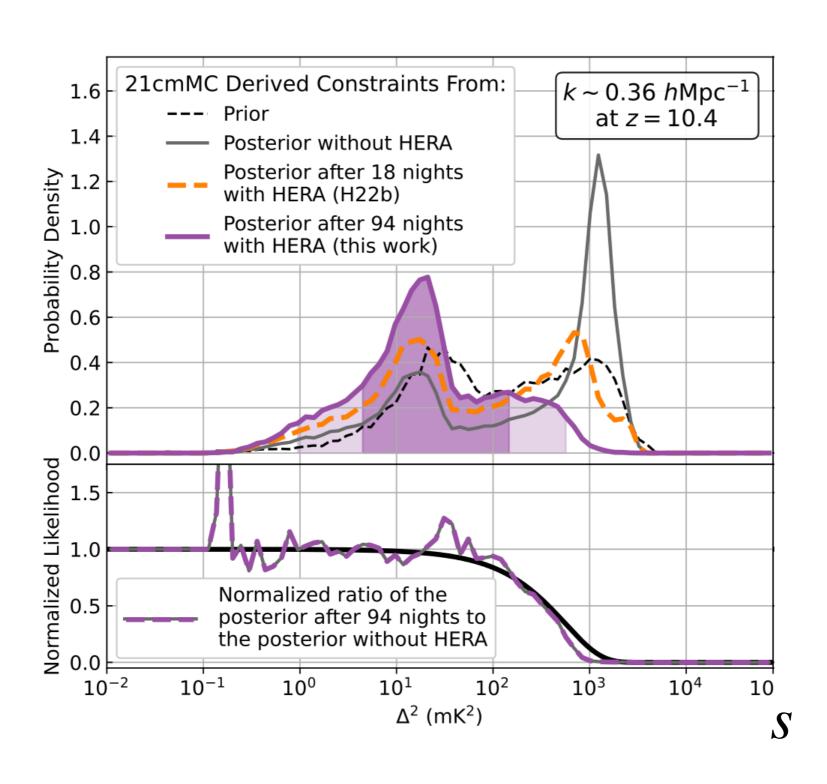
## 3 questions

- In what region does the brightest
   5% of the models live?
  - $\int_{?}^{\infty} P(d \mid s) P(s) \, ds$
- Given only our physics model, what are the brightest 5% of the models consistent with our data?
  - $\int_{?}^{\infty} P(d \mid s)$  (uniform prior) ds
- If we repeated our experiment, at what signal level would we have detection 95% of the time?
  - $\int_{d}^{\infty} P(d \mid s_{?}) \, \partial d$

Theory landscape question

Observer's question v1

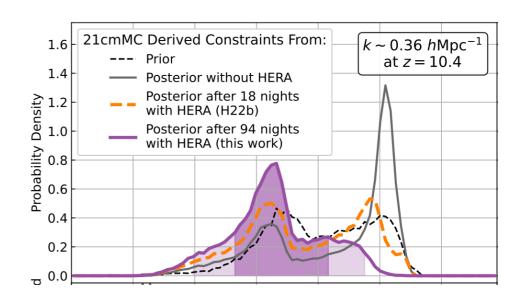
Observer's question v2



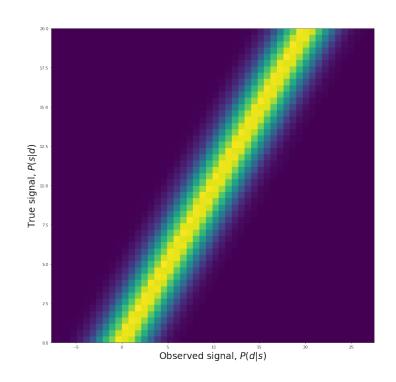
$$P(s \mid d) = P(d \mid s)P(s)$$

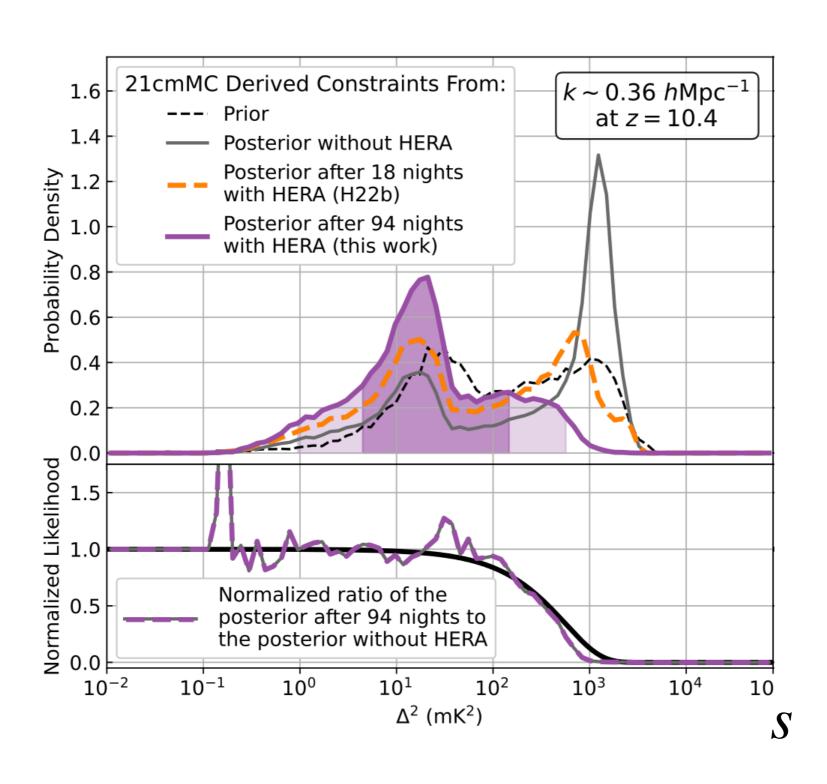
## 3 questions

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  - $\int_{d}^{\infty} P(d \mid s_{?}) \, \partial d$



## Same as above, but flat P(s)

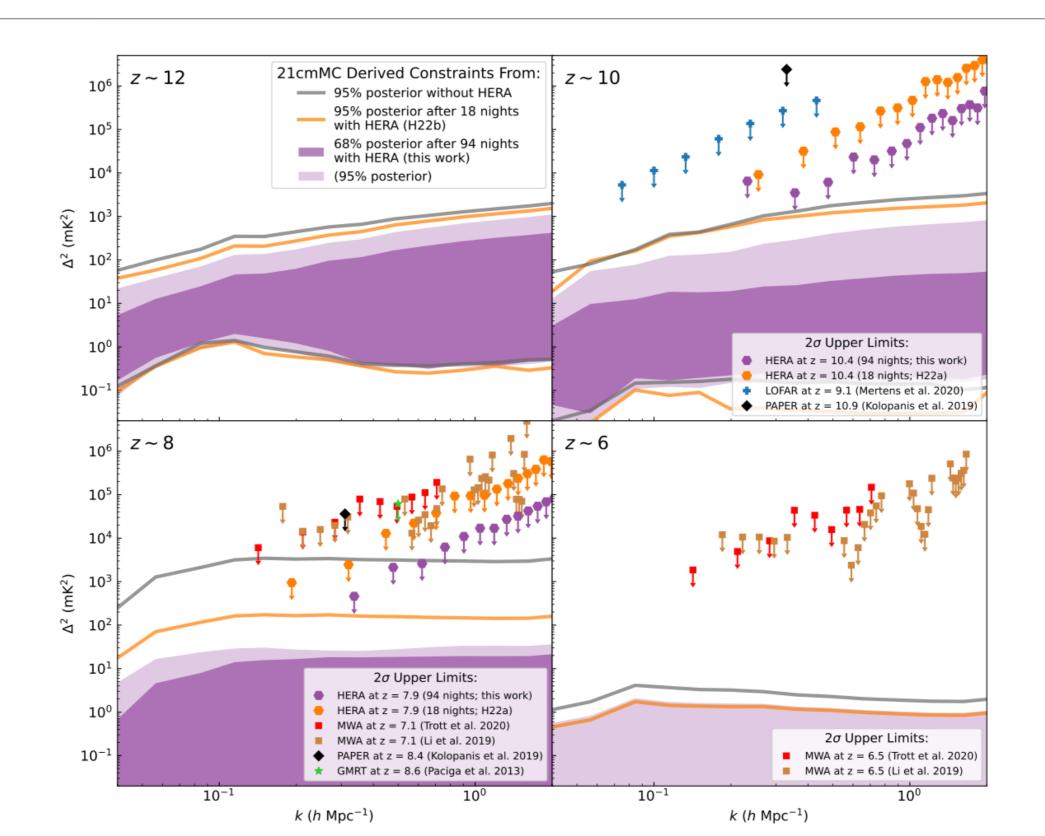




### Mistake is not in the math

- Theory landscape is a fine question, for a theorist
- Saying we have an observational upper limit (we'd see this signal 95% of the time) when what you calculated was fraction of theory landscape is wrong.
  - Math answered a different question

# Signature of 'shy' limits



## Priors

$$P(s \mid d) = \frac{P(d \mid s)P(s)}{P(d)}$$

To invert you need a prior P(s), key questions:

 Is your prior based on things you know? e.g. measurements, or strong theory constraints



**Use prior** 

 Is your prior based on assumptions, guesses, or convenience?



Flat prior or no prior

### Rules of thumb

- Data driven priors are fine
- You want your science conclusion to depend on your data, not on your prior → uninformative or flat priors
  - Flat priors
  - Priors that are flat over region of interest
- 'Frequentist' methods don't usually run into these problems (clearer question)